



Jet Propulsion Laboratory
California Institute of Technology



Differential absorption radar at 170 GHz for atmospheric boundary layer water vapor profiling

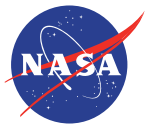
48th European Microwave Conference (EuRAD)

Madrid, Spain

September 26, 2018

Presenter: Richard Roy, JPL

**Coauthors: Ken Cooper, Matt Lebsock, Jose V. Siles, Luis Millán,
Raquel Rodriguez Monje, and Robert Dengler, JPL**



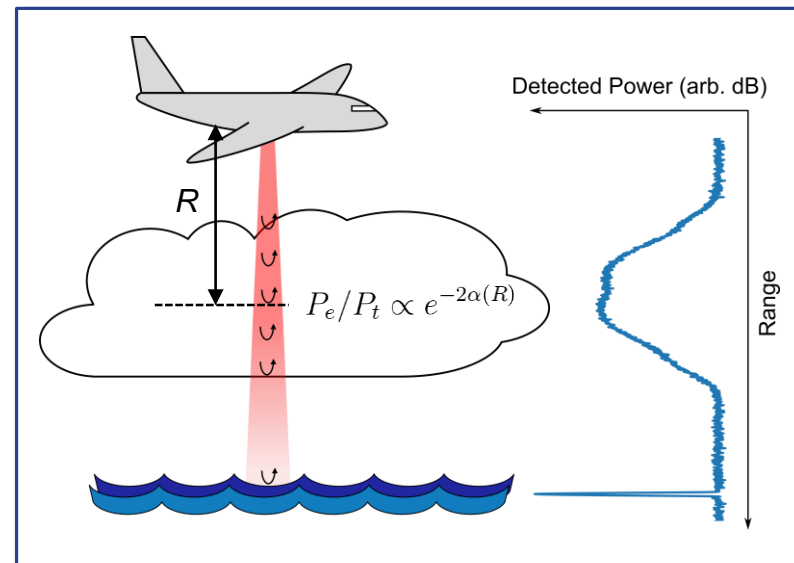
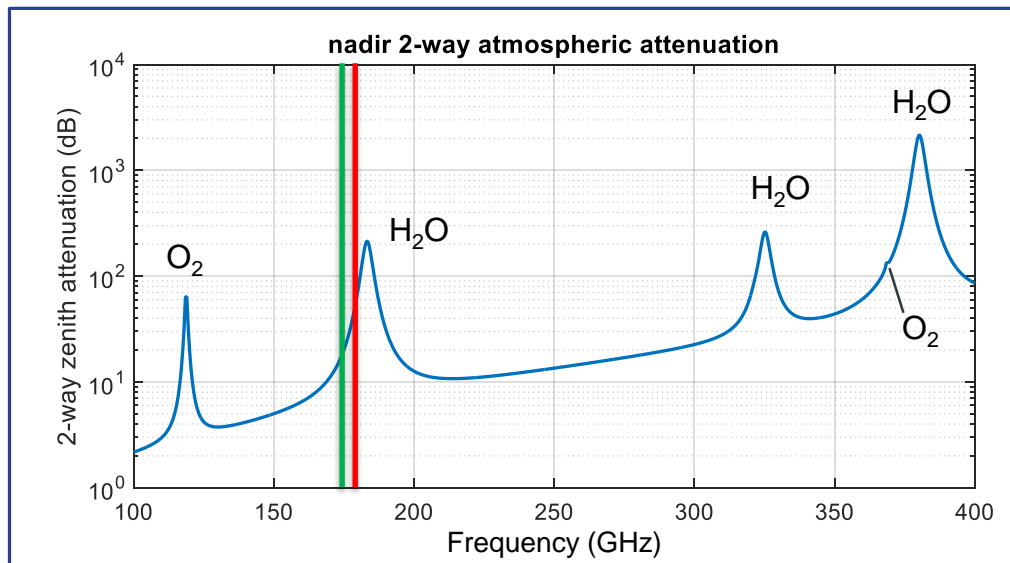
Problem:

- Existing remote sensing platforms have limited ability to retrieve *high-resolution, unbiased* water vapor profiles in the presence of clouds
- Problem recognized by NWP community (WMO, 2018):

“Critical atmospheric variables that are **not adequately measured** by current or planned systems are temperature and **humidity profiles** of adequate vertical resolution **in cloudy areas**.”

Proposed solution:

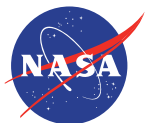
- Utilize range-resolved radar signal *and* frequency-dependent attenuation on flank of 183 GHz water vapor absorption line, so-called *differential absorption radar* (DAR)
- Microwave analog of differential absorption lidar (DIAL) – but can measure inside clouds (complementary observations)
- NASA Langley - prototype pressure sounder using O₂ differential absorption, no ranging [1]



- Differential reflectivity between two closely spaced frequencies proportional to absorbing gas density (integrated)

$$\text{dBZ}(r, f_1) - \text{dBZ}(r, f_2) \propto \int_0^r \rho_{\text{gas}}(r') dr'$$

- Important assumption:* Reflectivity and extinction from hydrometeors independent of frequency
- Frequency dependence from hardware cancels out (common mode)
- Airborne platform \Rightarrow Surface echoes (total column water)

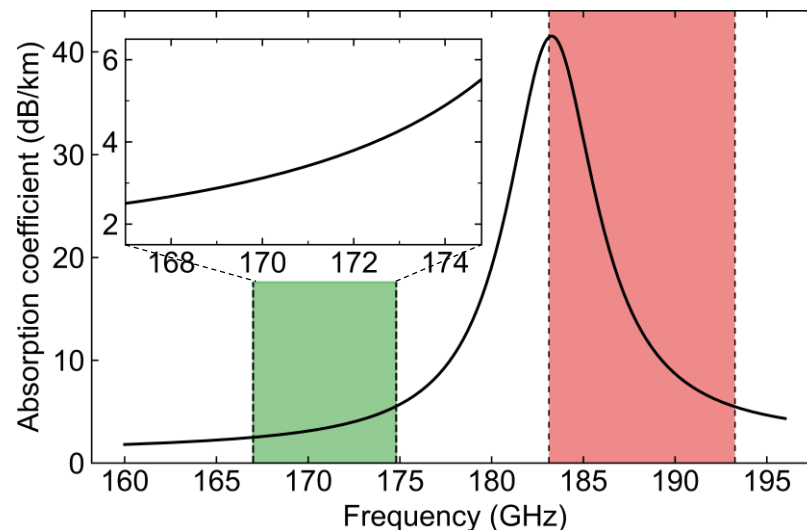


VIPR

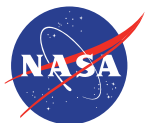
- Achievable transmit power $< 1\text{ W} \Rightarrow$ **FMCW mode of operation**
- Tunable across 167 to 174.8 GHz band
- Simultaneous cloud/vapor sounding
- Targets boundary layer clouds/precipitation and total column water vapor
- Demonstration flights on Twin Otter in 2019



VIPR frequency band

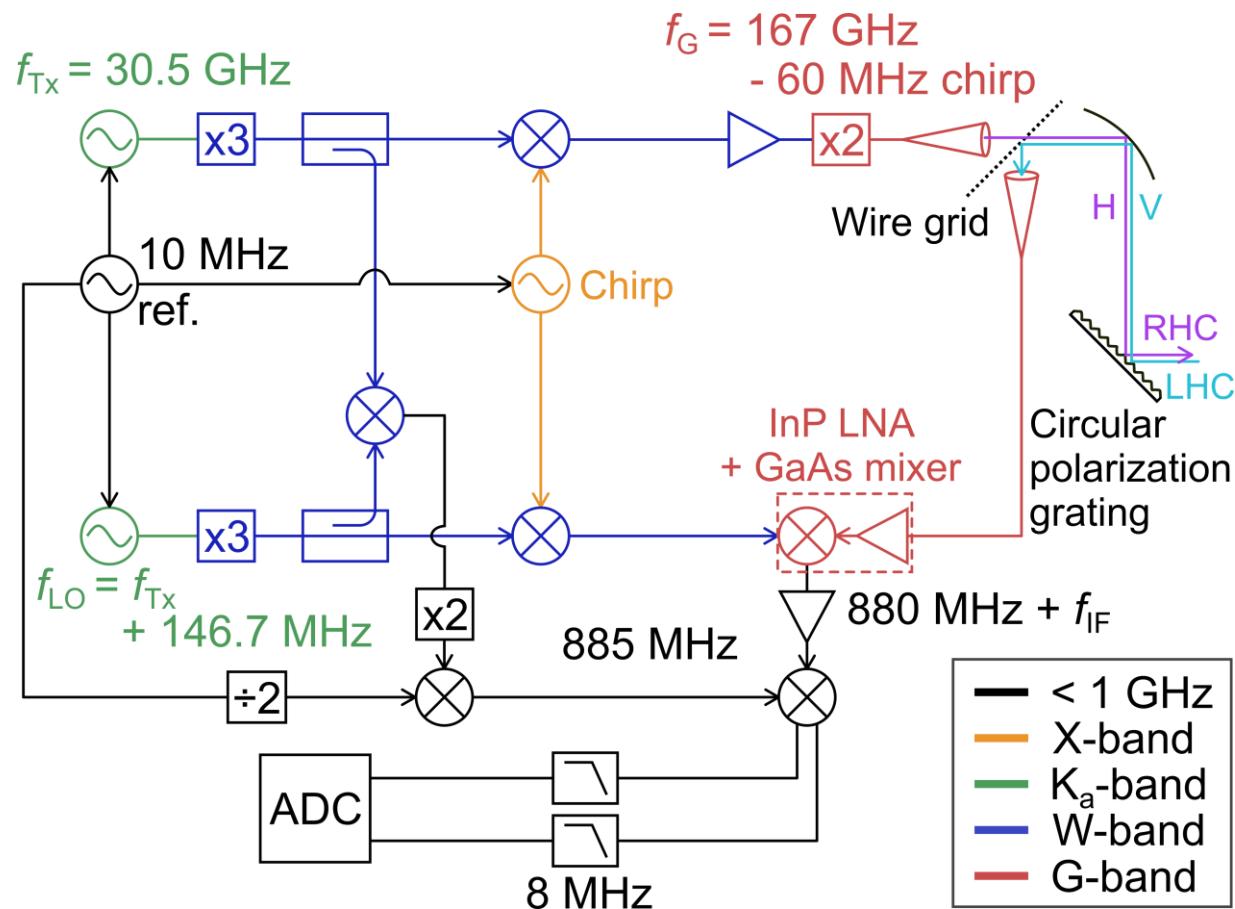


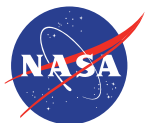
- Sensitivity to upper-tropospheric water vapor (ice clouds)
- Strong attenuation in planetary boundary layer (PBL)
- Transmission prohibited (passive sensors)
- Lower absolute absorption \Rightarrow sensitivity to PBL water vapor
- Profiling (PBL clouds/precipitation) and total column water measurement capabilities
- Fewer transmission restrictions



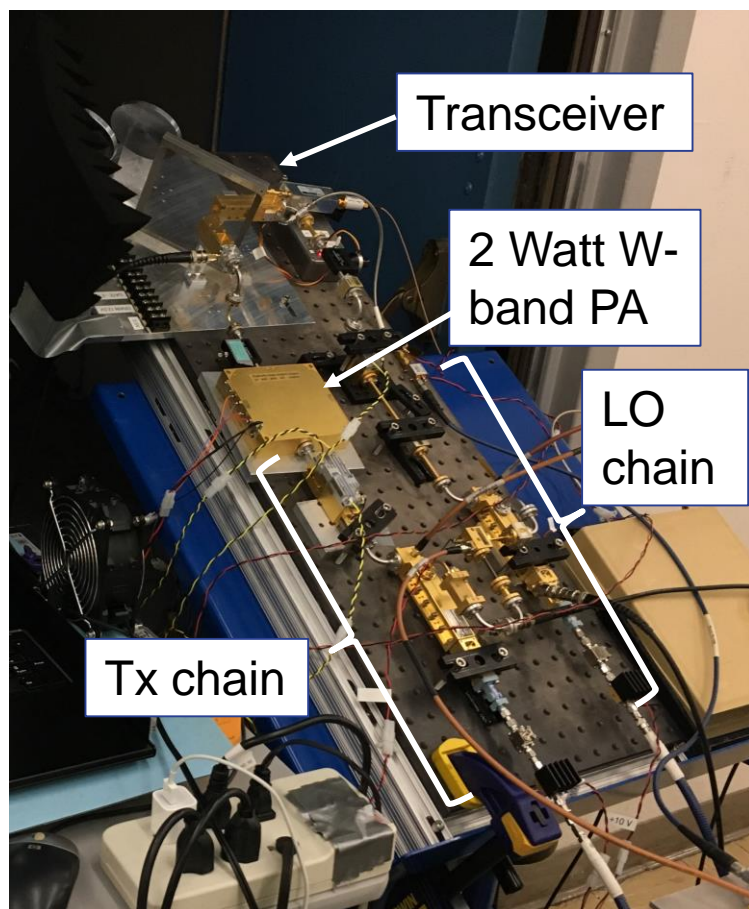
- Transmitter tunable from 167 to 174.8 GHz
- Nominal range resolution 2.5 m (60 MHz chirp bandwidth)
- Very high quasi-optical isolation permits simultaneous operation of Tx/Rx **and** single common aperture
- Oscillator phase-noise cancellation (homodyne) techniques enable thermal-noise-limited detection

170 GHz FMCW radar block diagram

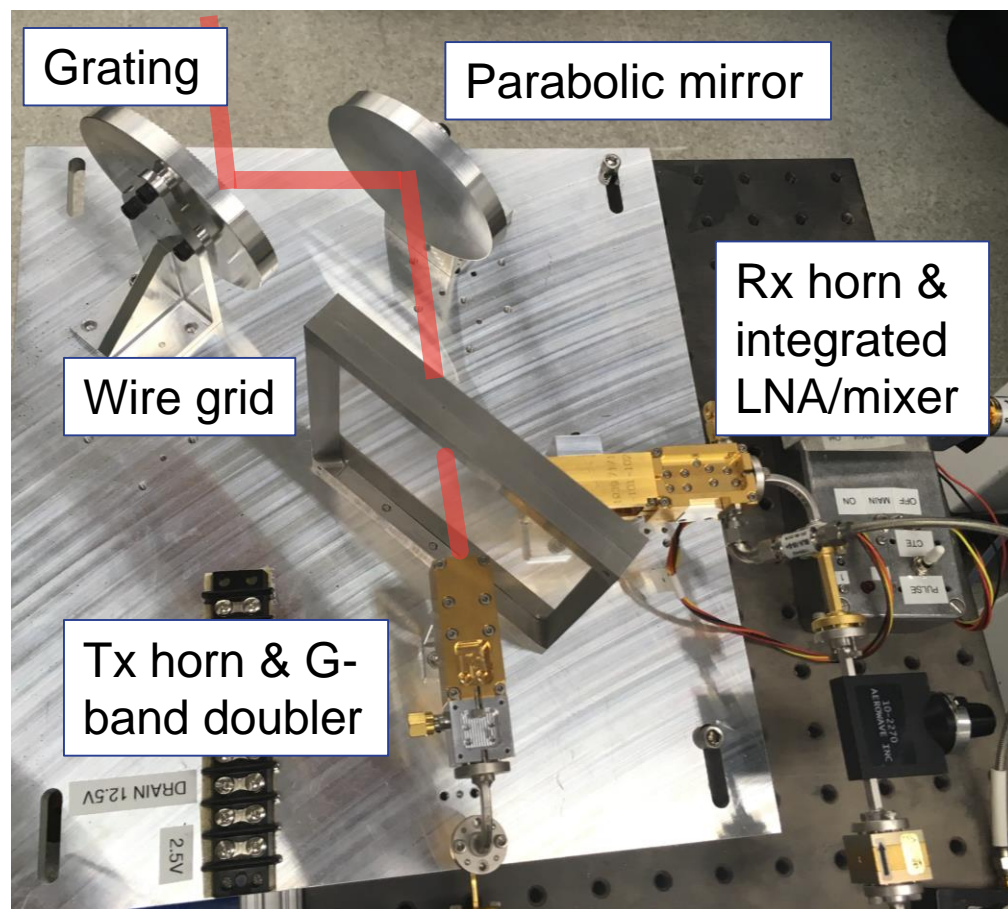




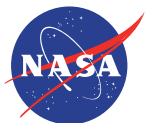
Radar front end



Transceiver

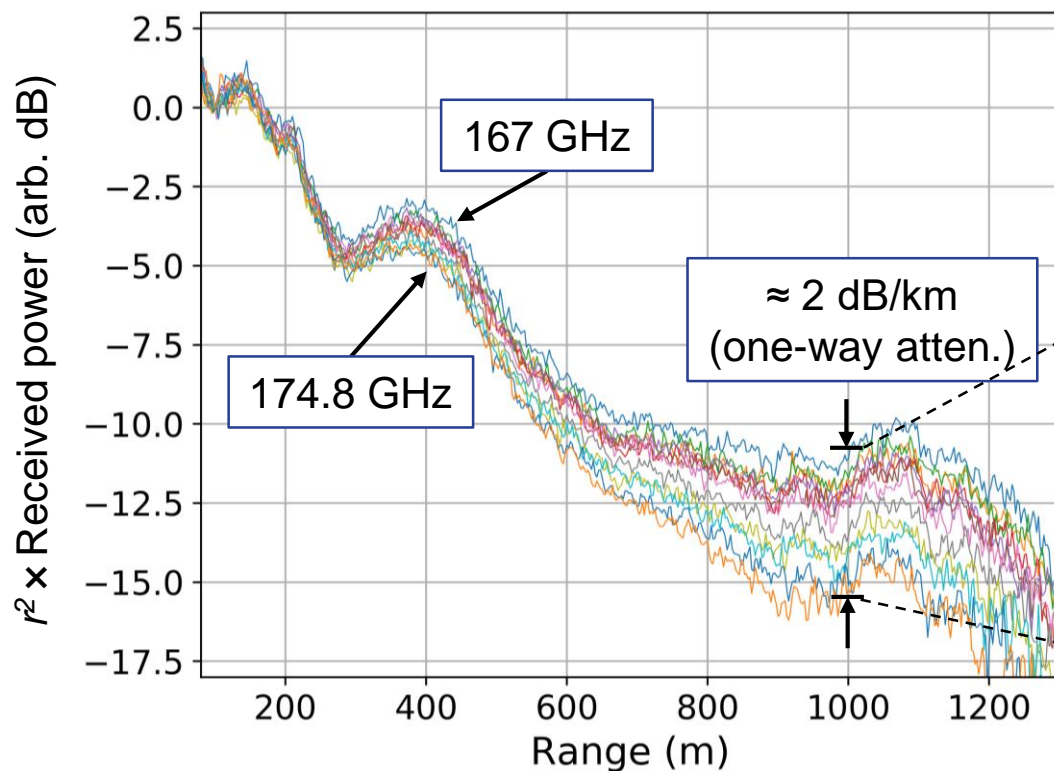


- 100 mW Tx power
 - 40 dB antenna gain
- } *Values for initial testing*



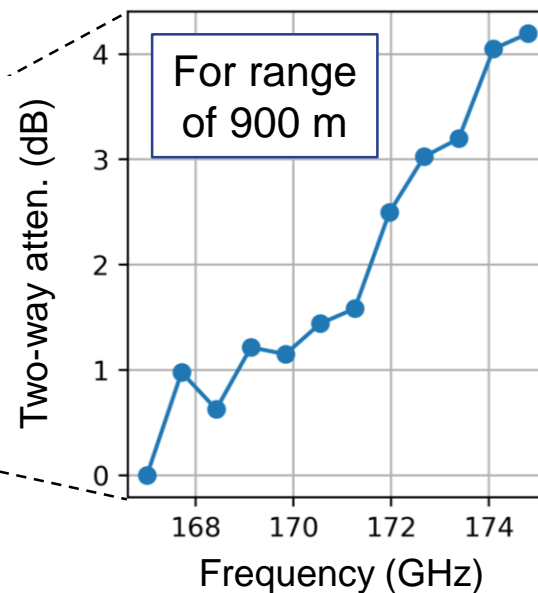
Precipitating clouds

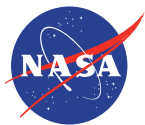
Power spectra normalized to values at 100 m



Reflectivity

$$r^2 P_e(r, f) \propto Z(r) e^{-2\alpha(r, f)}$$





- Differential measurement derived from ratio of *radar echo power* at two different ranges:

$$\frac{P_e(r_2, f)}{P_e(r_1, f)} \propto e^{-2\alpha(r_1, r_2, f)}, \quad \alpha(r_1, r_2, f) \propto \int_{r_1}^{r_2} \rho(r') dr'$$

One-way optical depth

- But the power we detect is the sum of the echo power *plus* the background noise power:

$$P_d(r, f) = P_e(r, f) + P_n(r, f)$$

- Note:

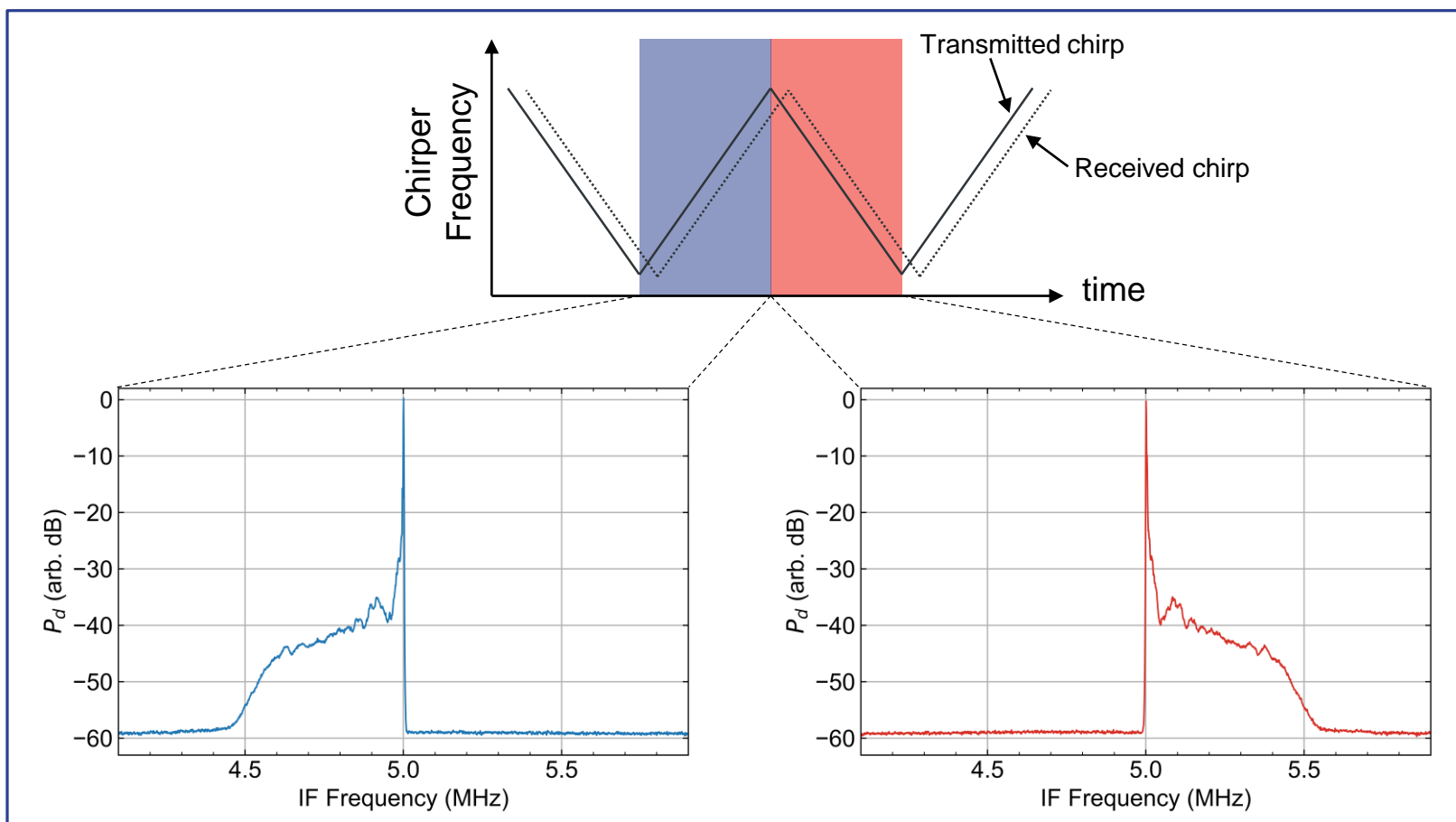
$$P_n(r, f) \neq \text{constant}$$

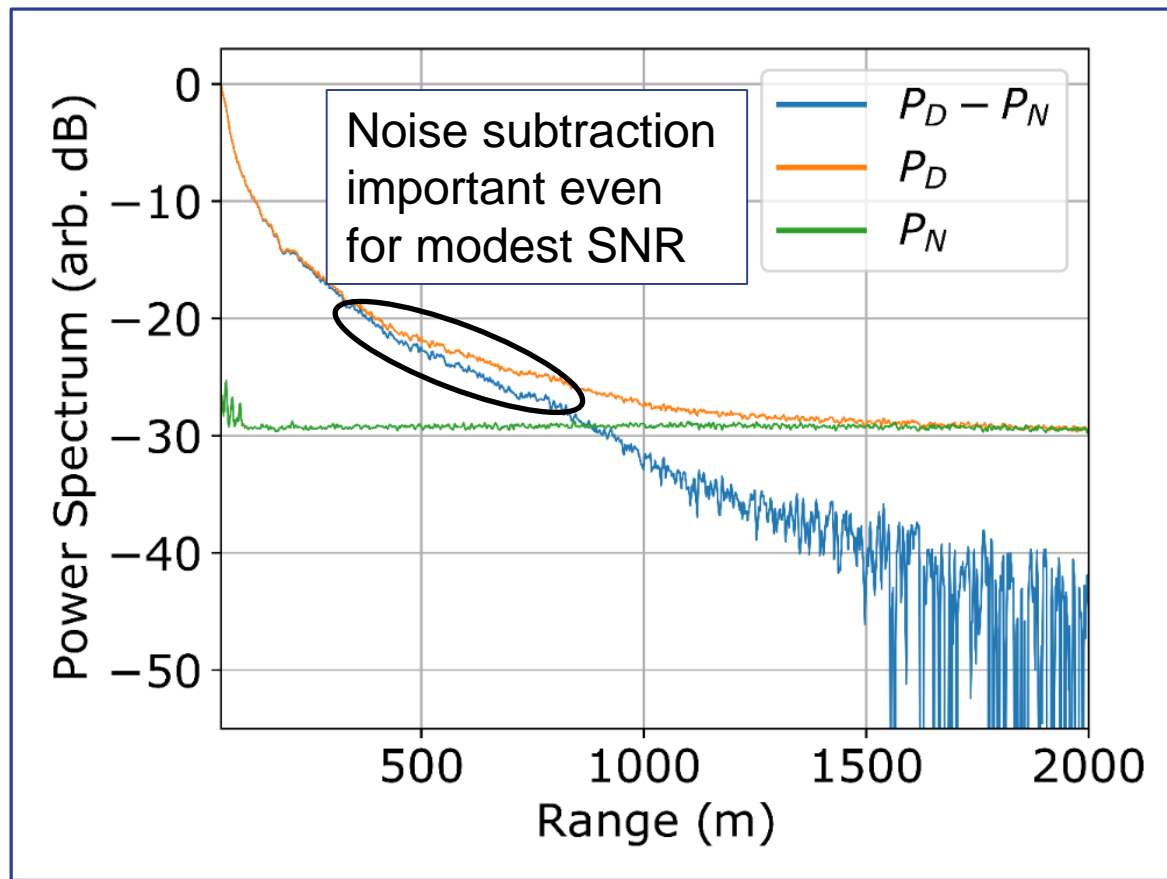
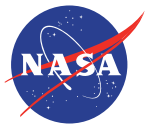
- Ripple in the radar IF spectrum
- Changing scene brightness temperature

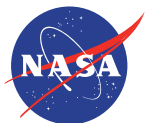
⇒ have to acquire and subtract true background noise floor – otherwise clear low-humidity bias for low-SNR



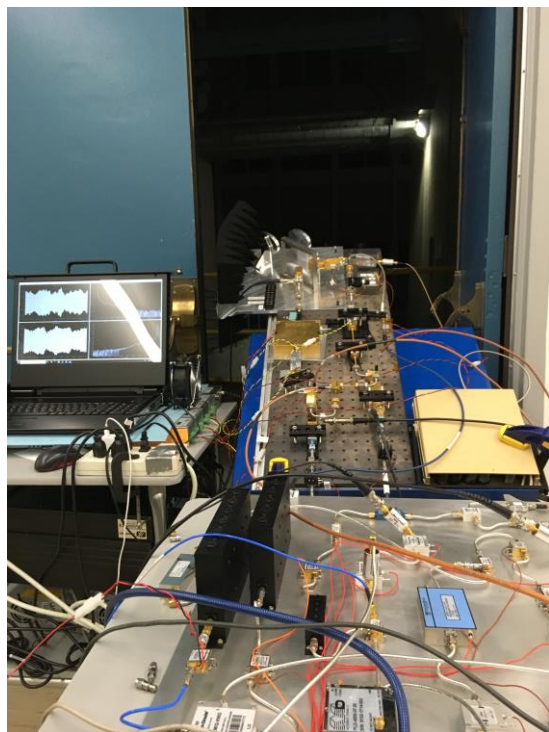
- Acquire cloud/rain signal spectrum **and** background noise floor simultaneously by using bidirectional chirp (triangle wave)



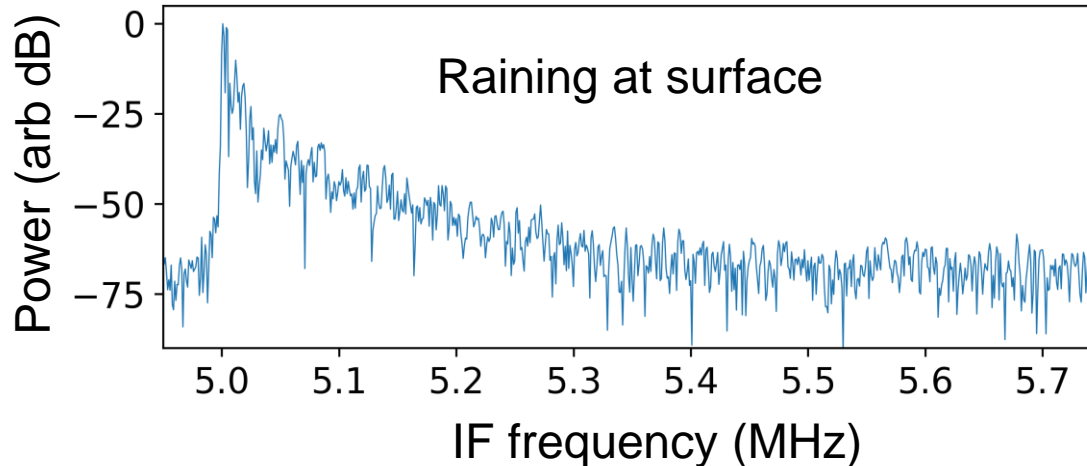
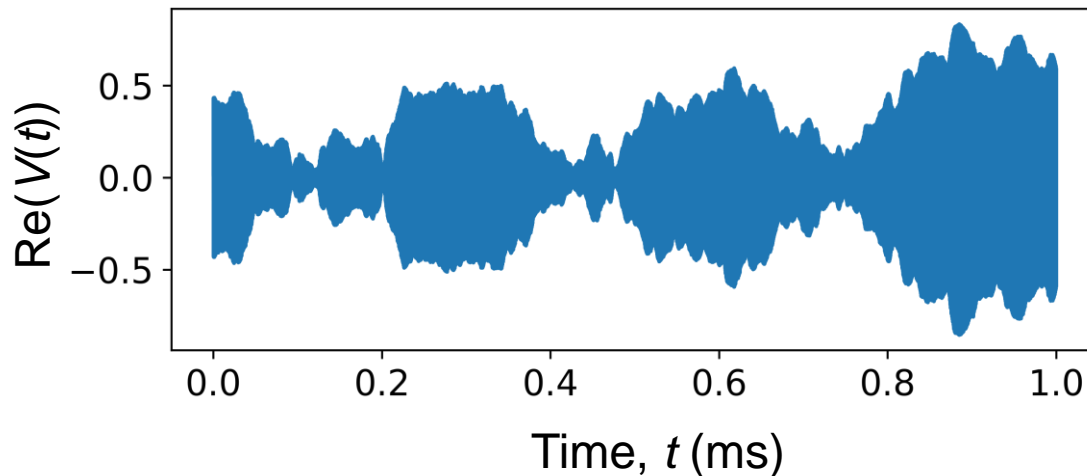


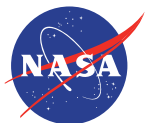


- Radar pointing 30° above horizontal
- $N = 2000$ chirps (1 ms) at each of 12 Tx frequencies
- Total meas. time = 25 sec

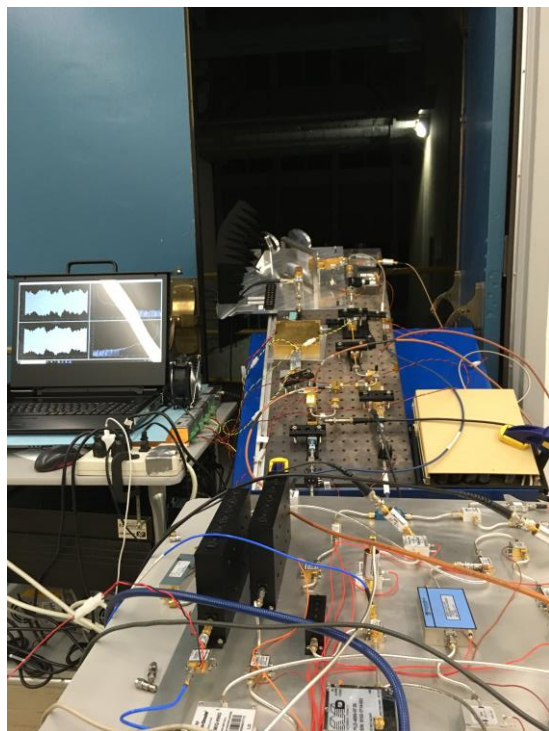


Downwards chirp

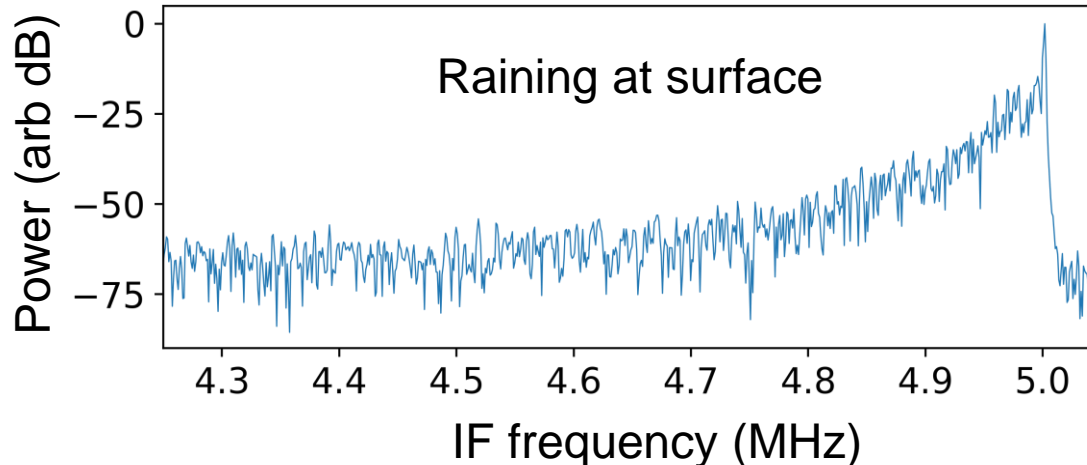
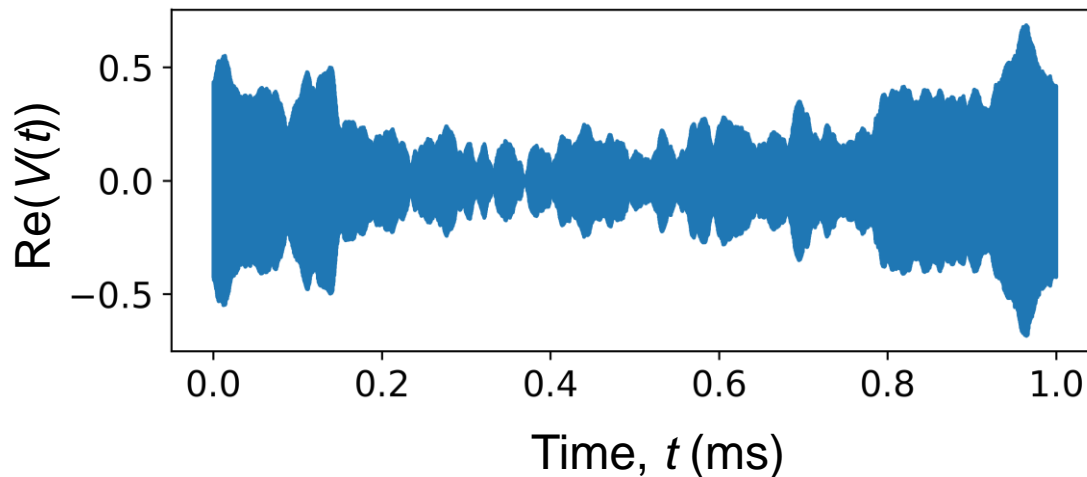


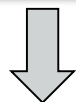
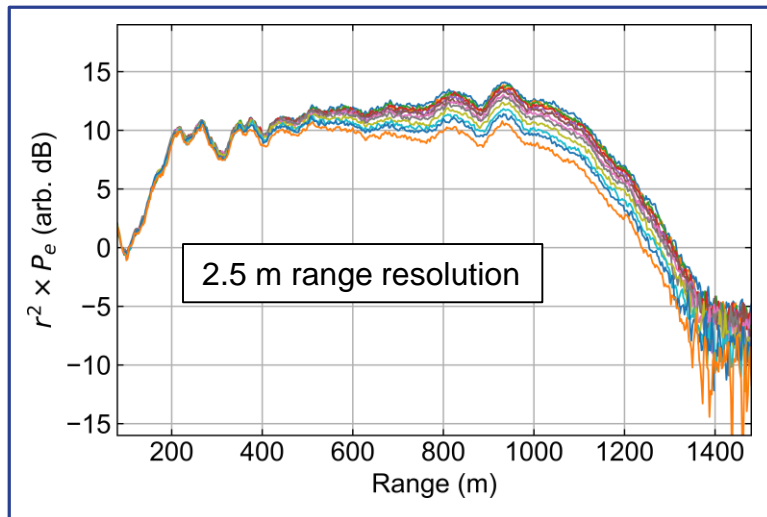
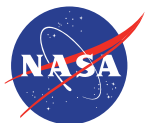


- Radar pointing 30° above horizontal
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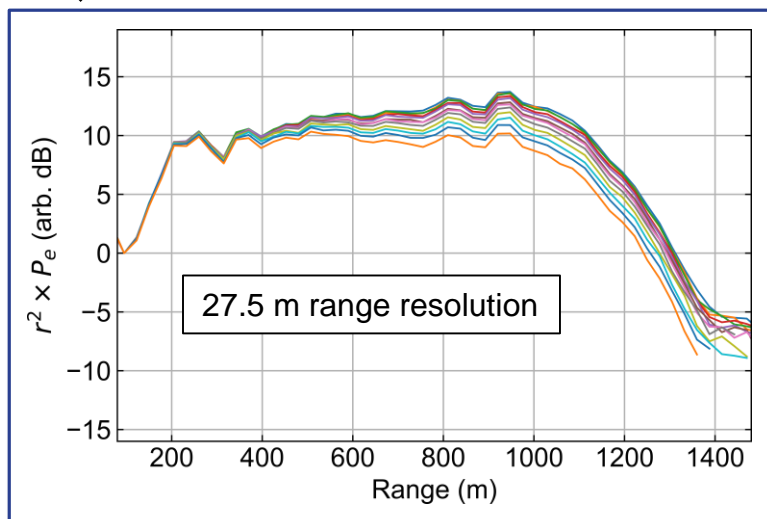


Upwards chirp

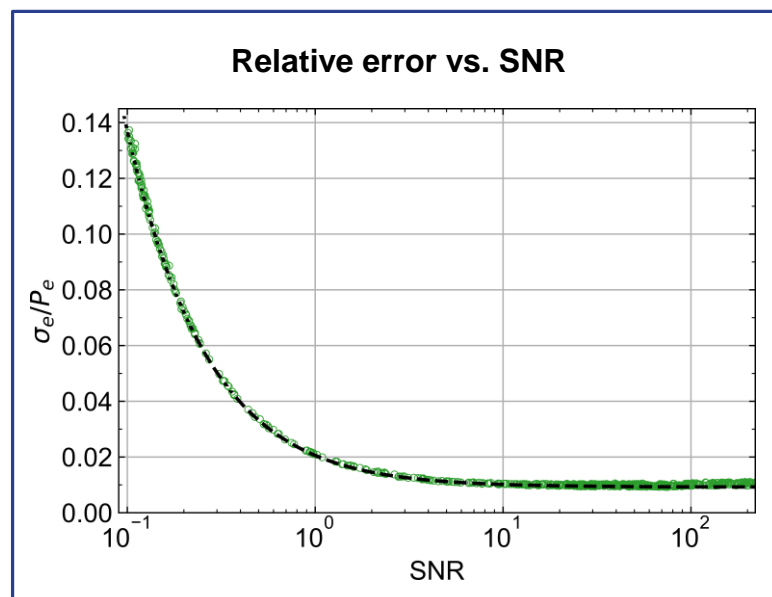




Bin (i.e. downsample) radar spectra by factor of 10 to reduce statistical uncertainty

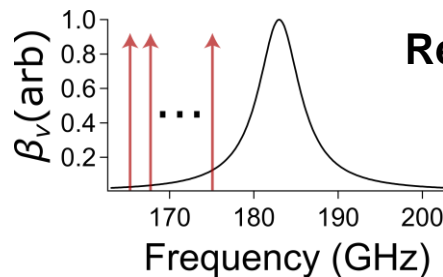


- Measurement error agrees very well with statistical model based on radar speckle noise

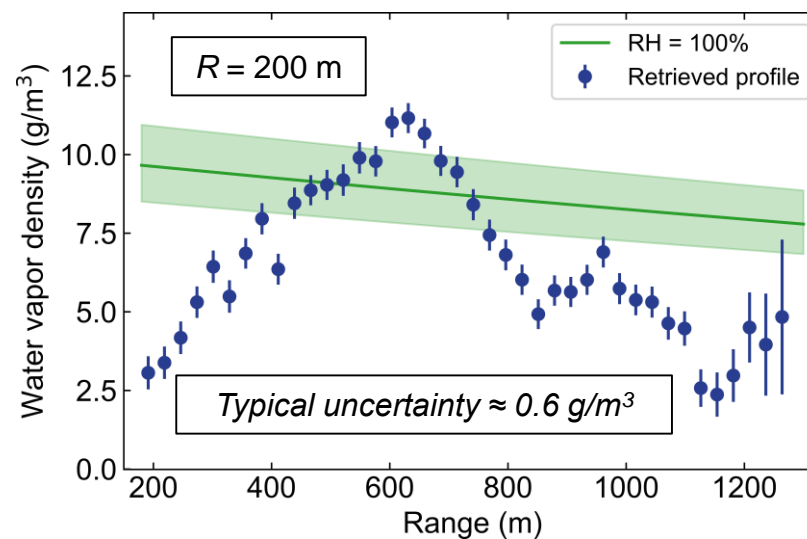
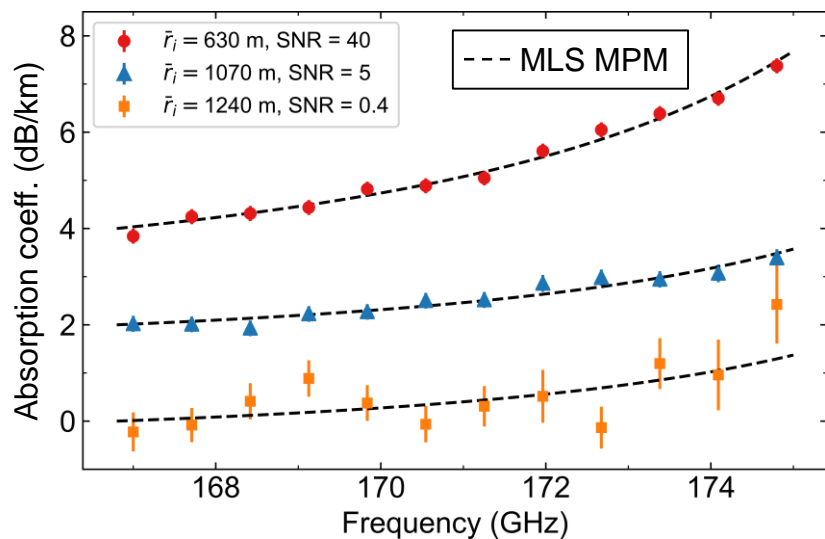
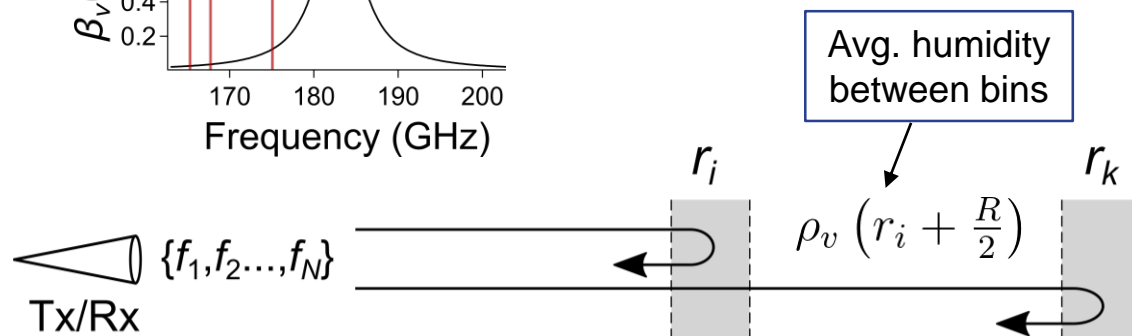


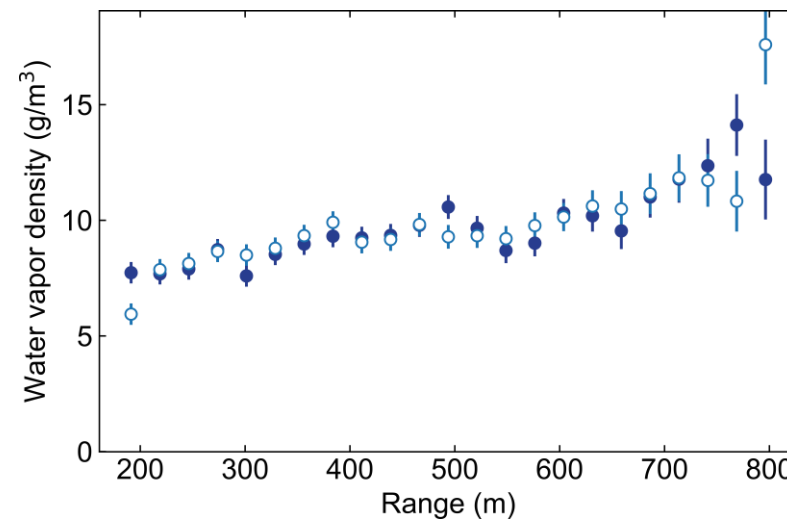
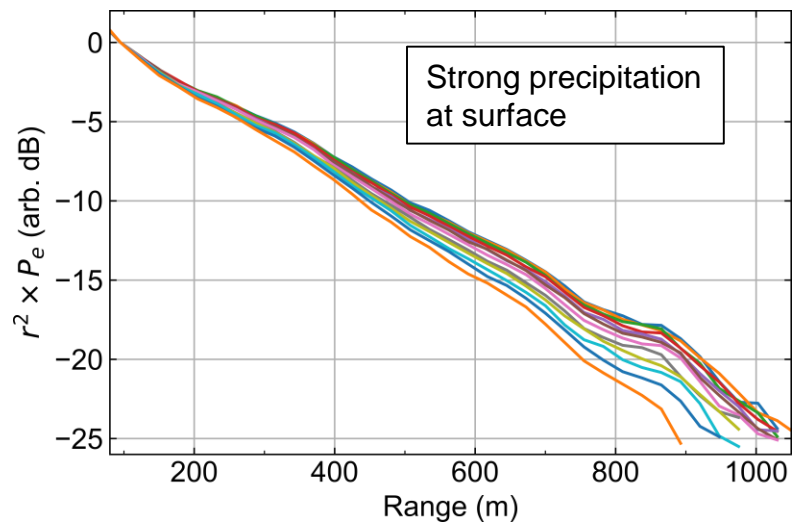
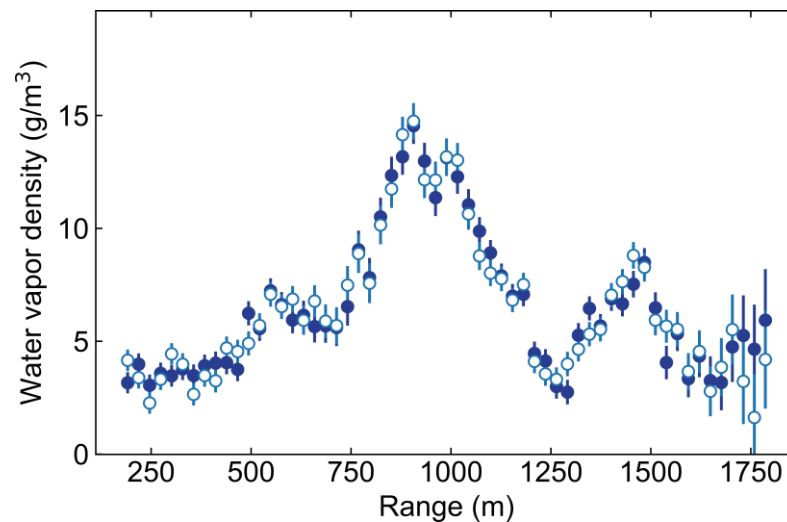
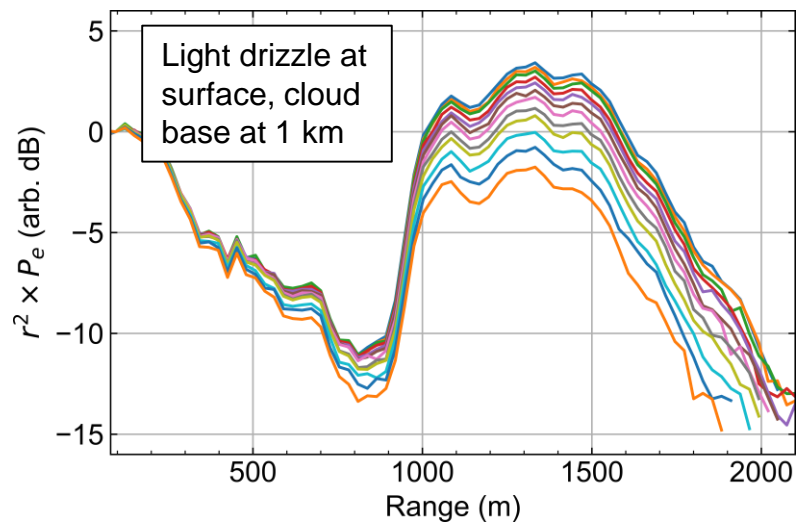
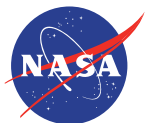
- Fit millimeter-wave propagation model to measured absorption coefficient $\beta_v(f)$ to extract humidity

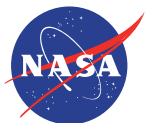
$$\beta_{\text{meas}} = \frac{-1}{2R} \ln \left(\frac{P_e(r_i + R, f)}{P_e(r_i, f)} \right)$$



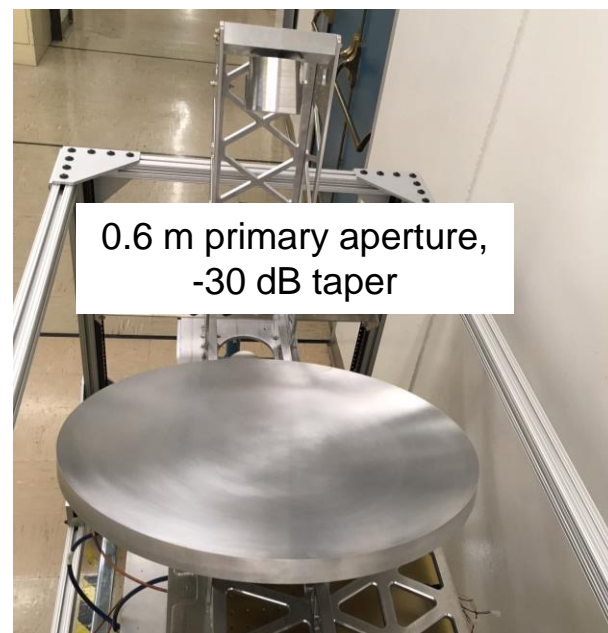
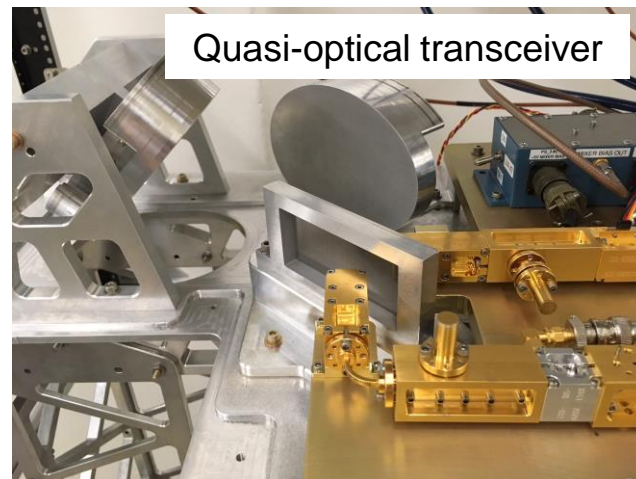
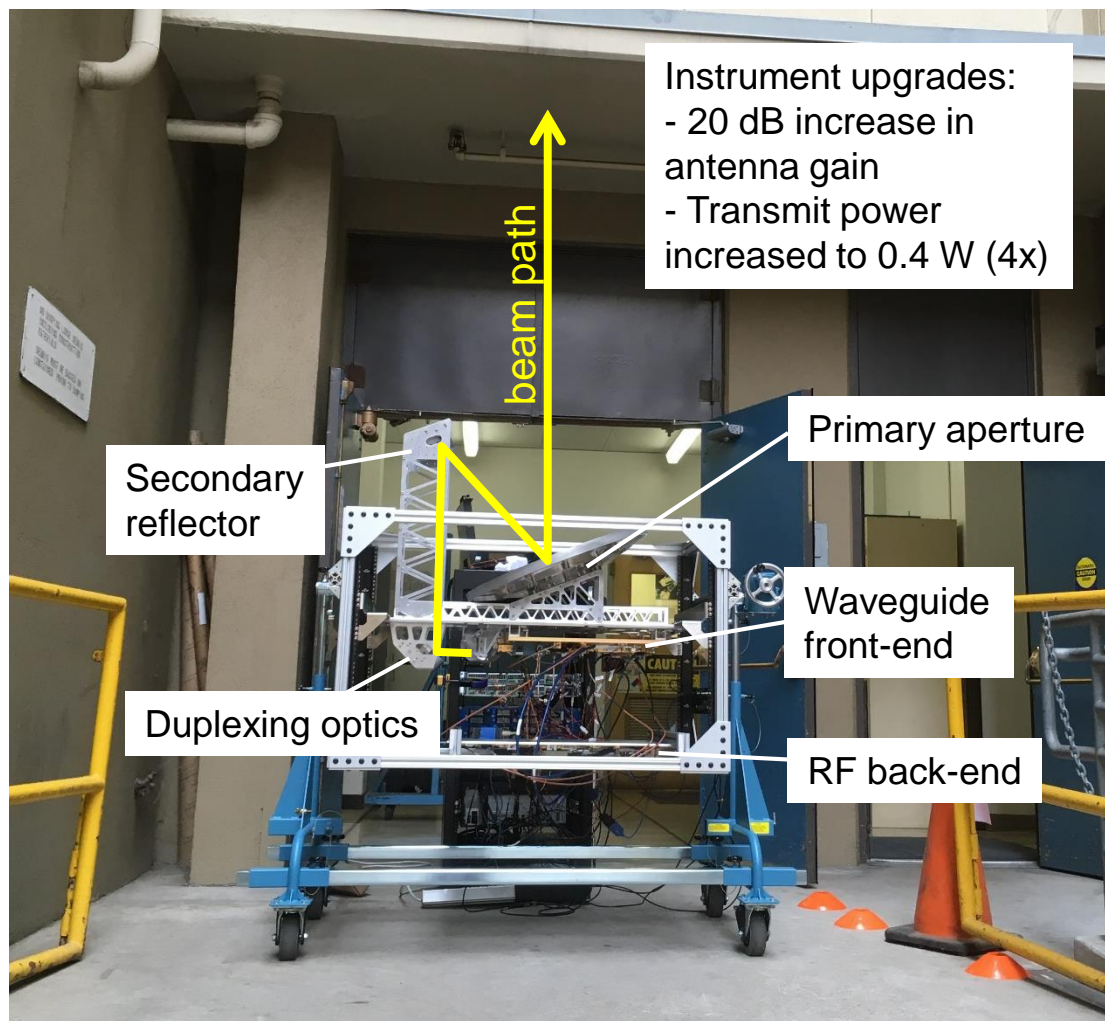
Retrieval step size: $r_k - r_i = R$

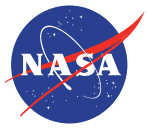




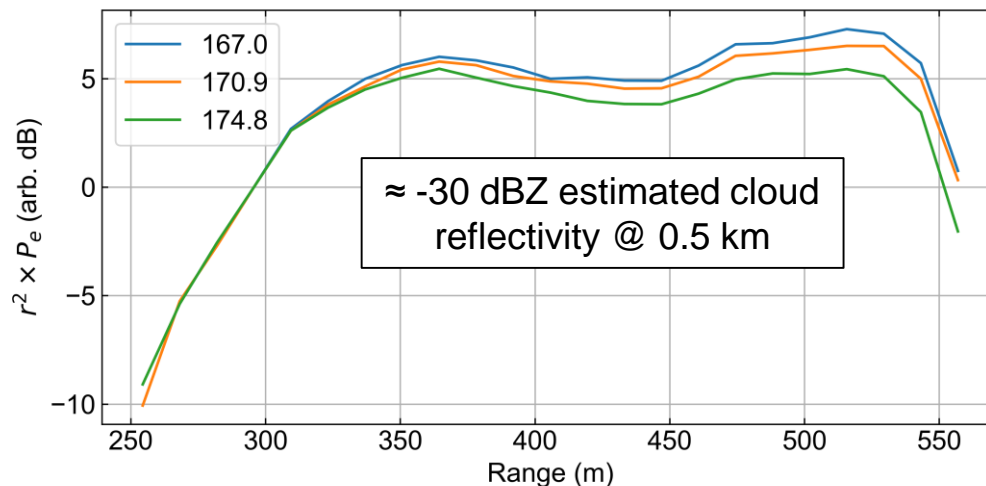
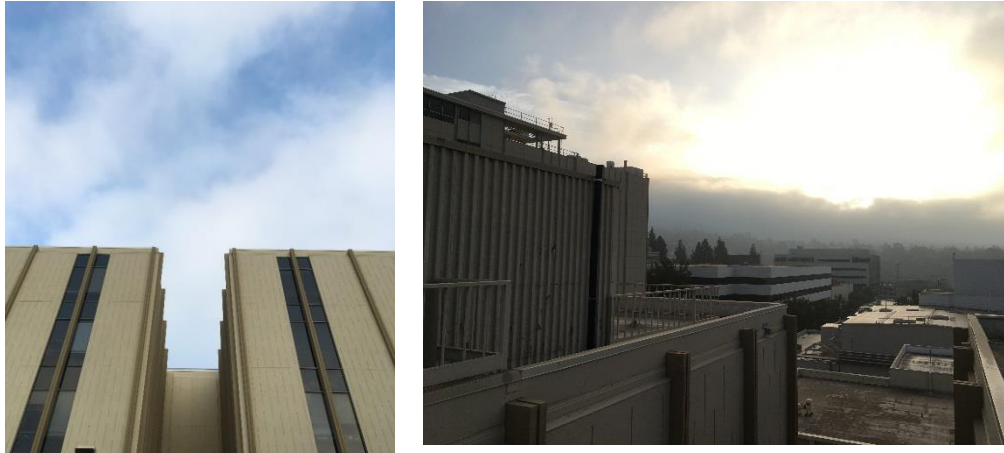


Airborne compatible VIPR system on Flotron rotation stage

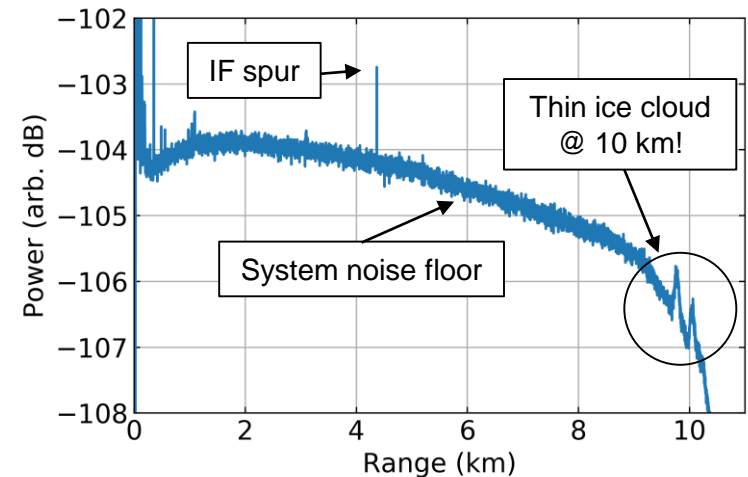




Morning low, tenuous clouds



Ground-based detection of upper-tropospheric ice cloud



**This is the world's first
G-band atmospheric
radar**



The present:

- G-Band differential absorption radar proof-of-concept instrument assembled and preliminary field testing successful
- First ever remotely sensed measurements of range-resolved humidity within clouds presented (*R. Roy et al., Atmos. Meas. Tech. Discuss., in review*)
- Signal processing and humidity inversion algorithms demonstrated
- Aircraft compatible architecture assembled and commencement of ground testing

The future:

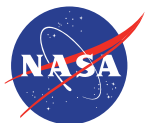
- Field testing with coincident radiosonde measurements for instrument validation
- Testing from an airborne platform – investigate surface returns for total column water retrieval

We are grateful to NASA's Earth Science Technology Office for supporting this project through the Instrument Incubator Program.

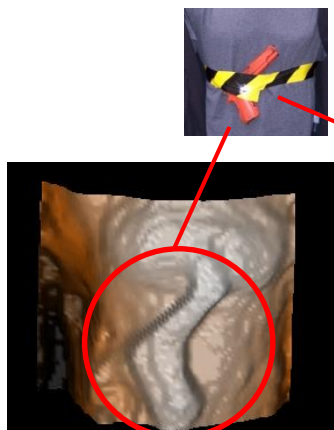


**Thank you for your
attention**

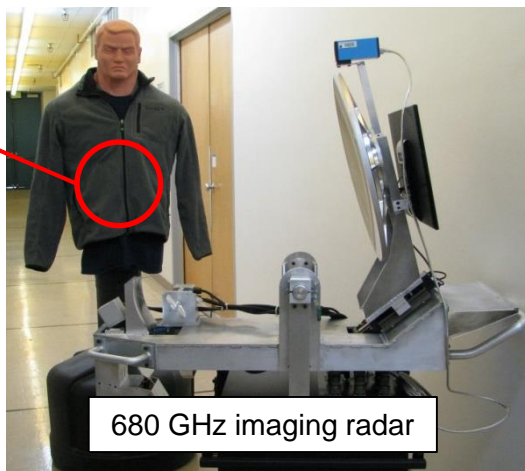
Questions?



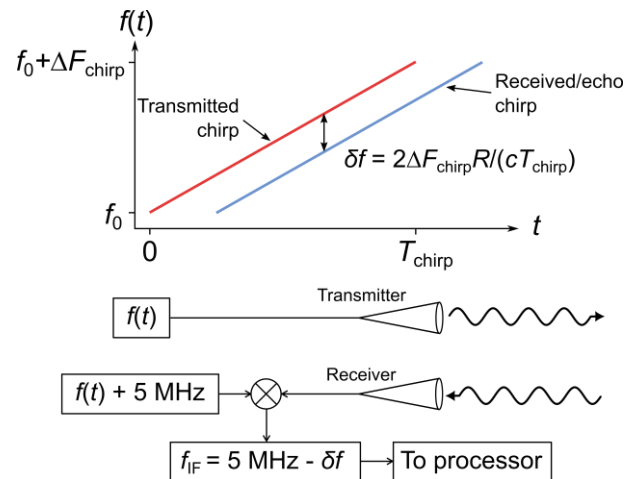
Frequency-modulated continuous-wave (FMCW) radar for security imaging



through-clothes detection

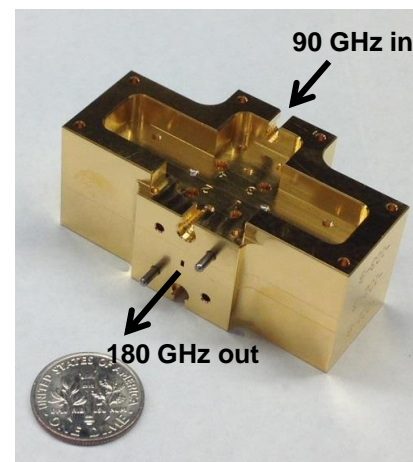
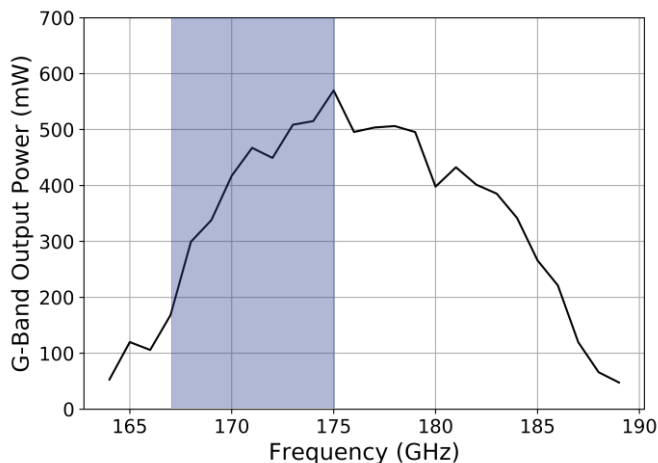


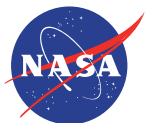
680 GHz imaging radar



- Extensive THz FMCW radar R&D for security imaging applications
- NASA funded effort for high-power solid-state sources near 183 GHz (ESTO ACT-13)
- State-of-the-art InP low-noise amplifiers developed for millimeter-wave radiometry and heterodyne spectroscopy

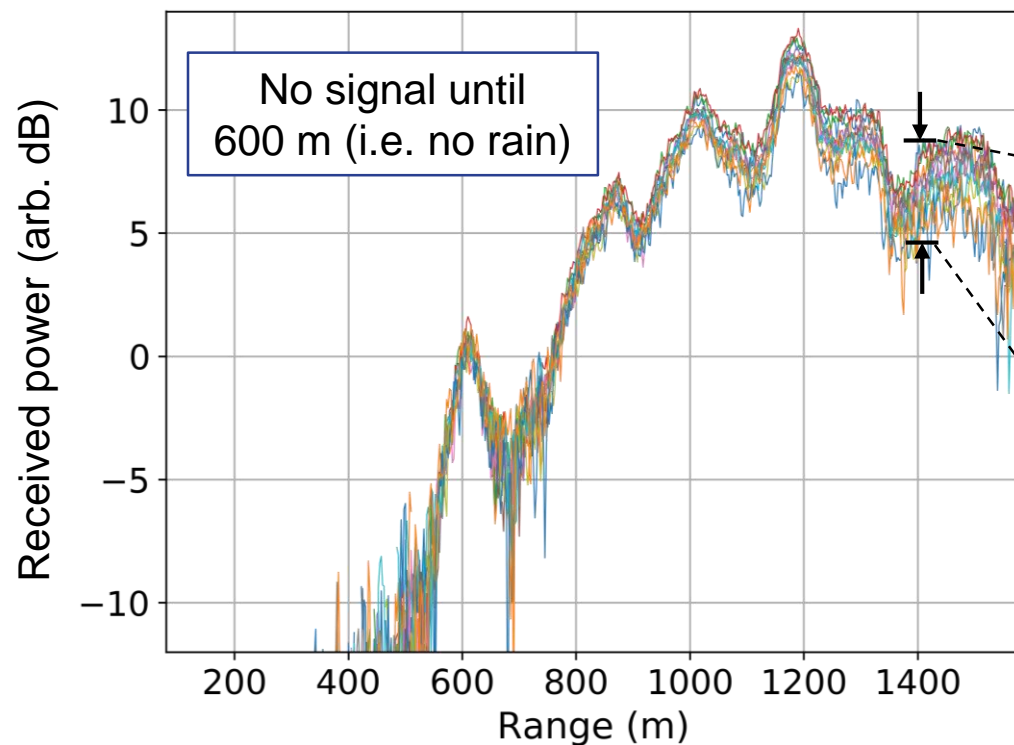
High output power G-band sources





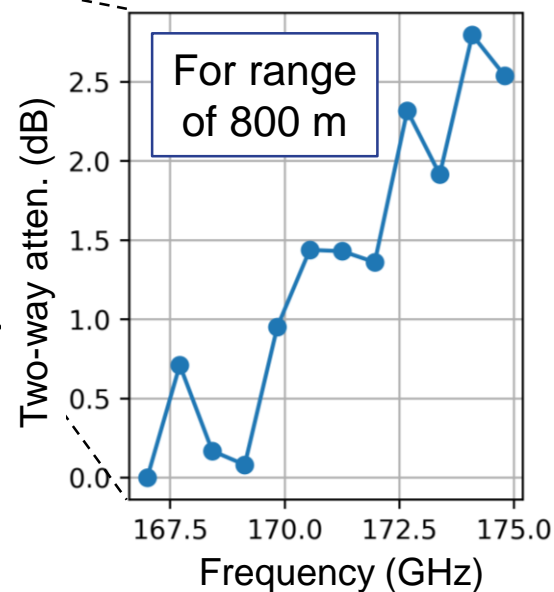
Non-precipitating clouds

Power spectra normalized to values at 600 m



Reflectivity

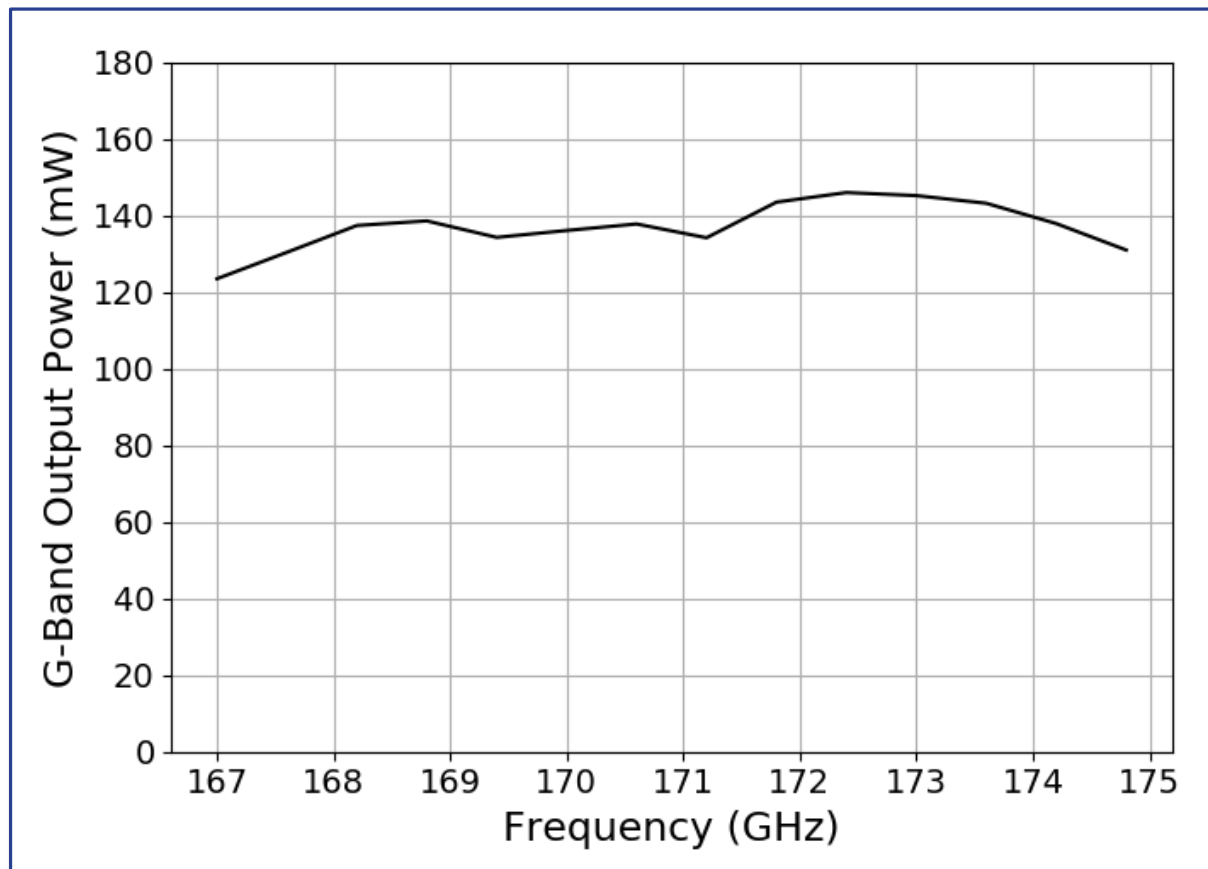
$$r^2 P_e(r, f) \propto Z(r) e^{-2\alpha(r, f)}$$

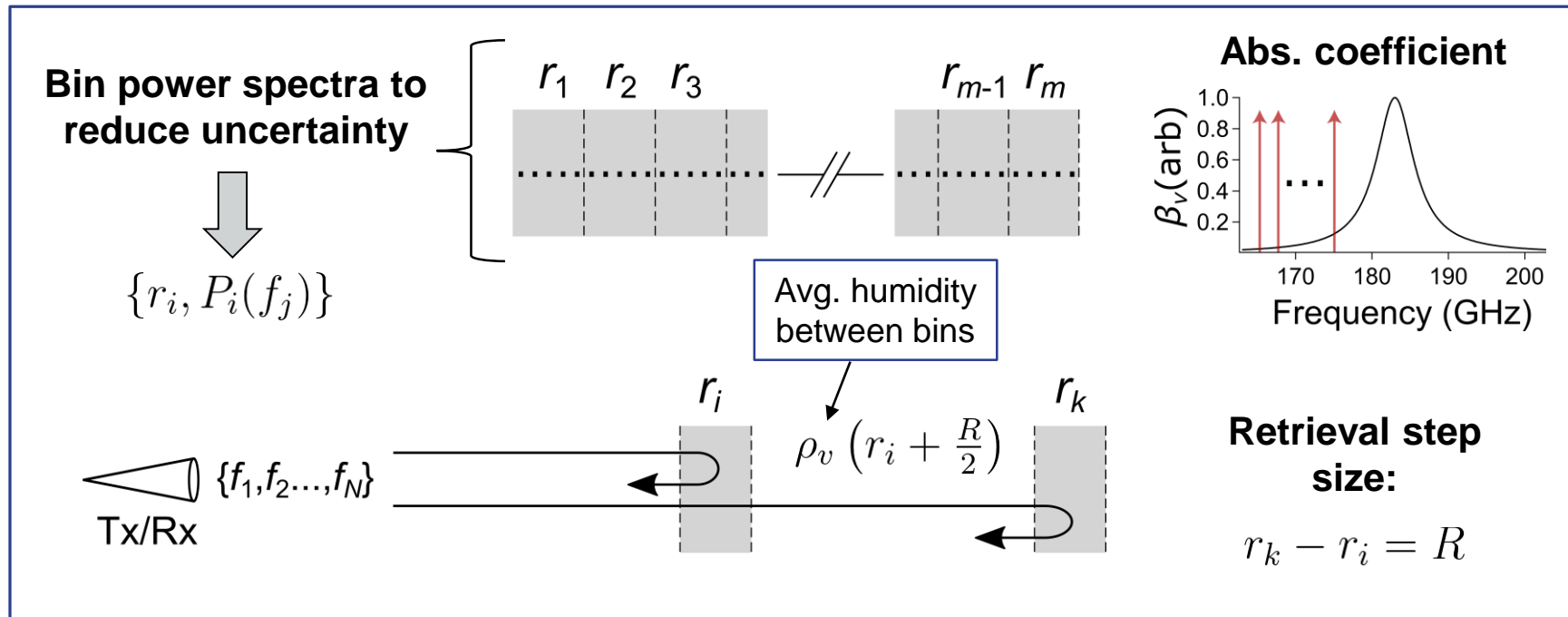
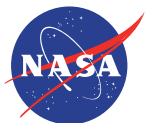




Single G-band frequency doubler (used in ground testing presented here):

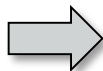
- ~400 mW W-band input
- ~30% efficiency



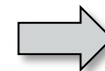


Retrieval algorithm:

Average N_p pulses for N frequencies, subtract noise floors, and bin resulting spectra to obtain $\{r_i, P_i(f_j)\}$



For each r_i , calculate $\ln \left(\frac{P_k(f_j)}{P_i(f_j)} \right)$ and fit known dependence $\beta_v(f)$ to measurements



Returns average humidity between each r_i and r_k , and therefore the profile with resolution R